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JM Wendlandt, SS Sastry - Decision and Control, 1994., Proceedings of the 33rd IEEE ..., 1994 - ieeexplore.ieee.org  
... useful for applications which do not need the full motion of the **Stewart platform**. ...  
consists of two platforms separated by rigid tubes and a **spring**-like device ...  
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CC Nguyen, SS Antrazi, ZL Zhou, CE Campbell Jr - Robotics and Automation, 1991. Proceedings., 1991 IEEE ..., 1991 - ieeexplore.ieee.org  
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mech- anism are used to suspend the lower compliant plat- form from the ...  
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JS Dai, DR Kerr - Proceedings of the Institution of Mechanical Engineers, Part ..., 2000 - journals.pepublishing.com  
... based on the **Stewart platform** ... The geometry of the device is based upon that  
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MM Svinin, S Hosoe, M Uchiyama - Robotics and Automation, 2001. Proceedings 2001 ICRA. IEEE ..., 2001 - ieeexplore.ieee.org  
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parallel linkages with the configuration known as the **Stewart platform**. ...  
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... have proved much of the theory and performance of a **Stewart Platform** parallel link ...  
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